# Assignment -4

Distance Detection Using Ultrasonic Sensor

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| Assignment Date | 25 October 2022 |
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| Maximum Marks | 2 Marks |

# Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

WOKWI LINK: https://wokwi.com/projects/346574219953308244

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| --- |
| **CODE:** |
| #include <WiFi.h>//library for wifi #include  <PubSubClient.h>//library for MQtt  void callback(char\* subscribetopic, byte\* payload, unsigned intpayloadLength);  //-------credentials of IBM Accounts------  #define ORG "f59trs"//IBM ORGANITION ID  #define DEVICE\_TYPE "ultrasonicsensor"//Device type mentioned inibm watson IOT Platform  #define DEVICE\_ID "distancedetection"//Device ID mentioned in ibmwatson IOT Platform  #define TOKEN "AlGMGaaF01nawa1QA3" //Token String data3;  float dist;  //-------- Customise the above values --------  char server[] = ORG ".messaging.internetofthings.ibmcloud.com";//Server Name  char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name andtype of event perform and format in which data to be send  char subscribetopic[] = "iot-2/cmd/test/fmt/String";//  cmd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING  char authMethod[] = "use-token-auth";// authentication methodchar token[] = TOKEN; char clientId[] = "d:" ORG ":" DEVICE\_TYPE ":" DEVICE\_ID;//clientid  // -  WiFiClient wifiClient; // creating the instance for wificlient |

PubSubClient client(server, 1883, callback ,wifiClient);

//calling the predefined client id by passing parameter likeserver id,portand wificredential

int LED = 4; int trig = 5; int echo = 18;void setup()

{

**Serial**.begin(115200); pinMode(trig,OUTPUT); pinMode(echo,INPUT); pinMode(LED, OUTPUT); delay(10); wificonnect(); mqttconnect();

}

void loop()// Recursive Function

{

digitalWrite(trig,LOW); digitalWrite(trig,HIGH); delayMicroseconds(10); digitalWrite(trig,LOW);

float dur = pulseIn(echo,HIGH);float dist

= (dur \* 0.0343)/2; **Serial**.print ("Distancein cm");**Serial**.println(dist);

PublishData(dist); delay(1000);

if (!client.loop()) { mqttconnect();

}

}

/\* retrieving to

Cloud \*/

void PublishData(float dist) { mqttconnect();//function call for connecting to ibm

/\*

creating the String in in form JSon to update the data toibm cloud

\*/

String object;

if (dist <100)

{

digitalWrite(LED,HIGH); **Serial**.println("object is near");object = "Near";

}

else

{

digitalWrite(LED,LOW); **Serial**.println("no object found");object = "No";

}

String payload = "{\"distance\":";payload += dist;

payload += "," "\"object\":\"";payload += object;

payload += "\"}";

**Serial**.print("Sending payload: ");

**Serial**.println(payload);

if (client.publish(publishTopic, (char\*) payload.c\_str())) {

**Serial**.println("Publish ok");// if it sucessfully upload dataon the cloud then it will print publish ok in Serial monitor or else it will print publish failed

} else {

**Serial**.println("Publish failed");

}

}

void mqttconnect() {

if (!client.connected()) { **Serial**.print("Reconnecting client to ");**Serial**.println(server);

while (!!!client.connect(clientId, authMethod, token)) {

**Serial**.print("."); delay(500);

}

initManagedDevice();

**Serial**.println();

}

}

void wificonnect() //function defination for wificonnect

{

**Serial**.println(); **Serial**.print("Connecting to ");

WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentialsto establish the connection

while (WiFi.status() != WL\_CONNECTED) { delay(500);

**Serial**.print(".");

}

**Serial**.println(""); **Serial**.println("WiFi connected");**Serial**.println("IP address: "); **Serial**.println(WiFi.localIP());

}

void initManagedDevice() {

if (client.subscribe(subscribetopic)) { **Serial**.println((subscribetopic)); **Serial**.println("subscribe to cmd OK");

} else {

**Serial**.println("subscribe to cmd FAILED");

}

}

void callback(char\* subscribetopic, byte\* payload, unsigned intpayloadLength)

{

**Serial**.print("callback invoked for topic: ");

**Serial**.println(subscribetopic);

for (int i = 0; i < payloadLength; i++) {

//Serial.print((char)payload[i]);data3 += (char)payload[i];

}

// Serial.println("data: "+ data3);

// if(data3=="Near")

// {

// Serial.println(data3);

// digitalWrite(LED,HIGH);

// }

// else

// {

// Serial.println(data3);

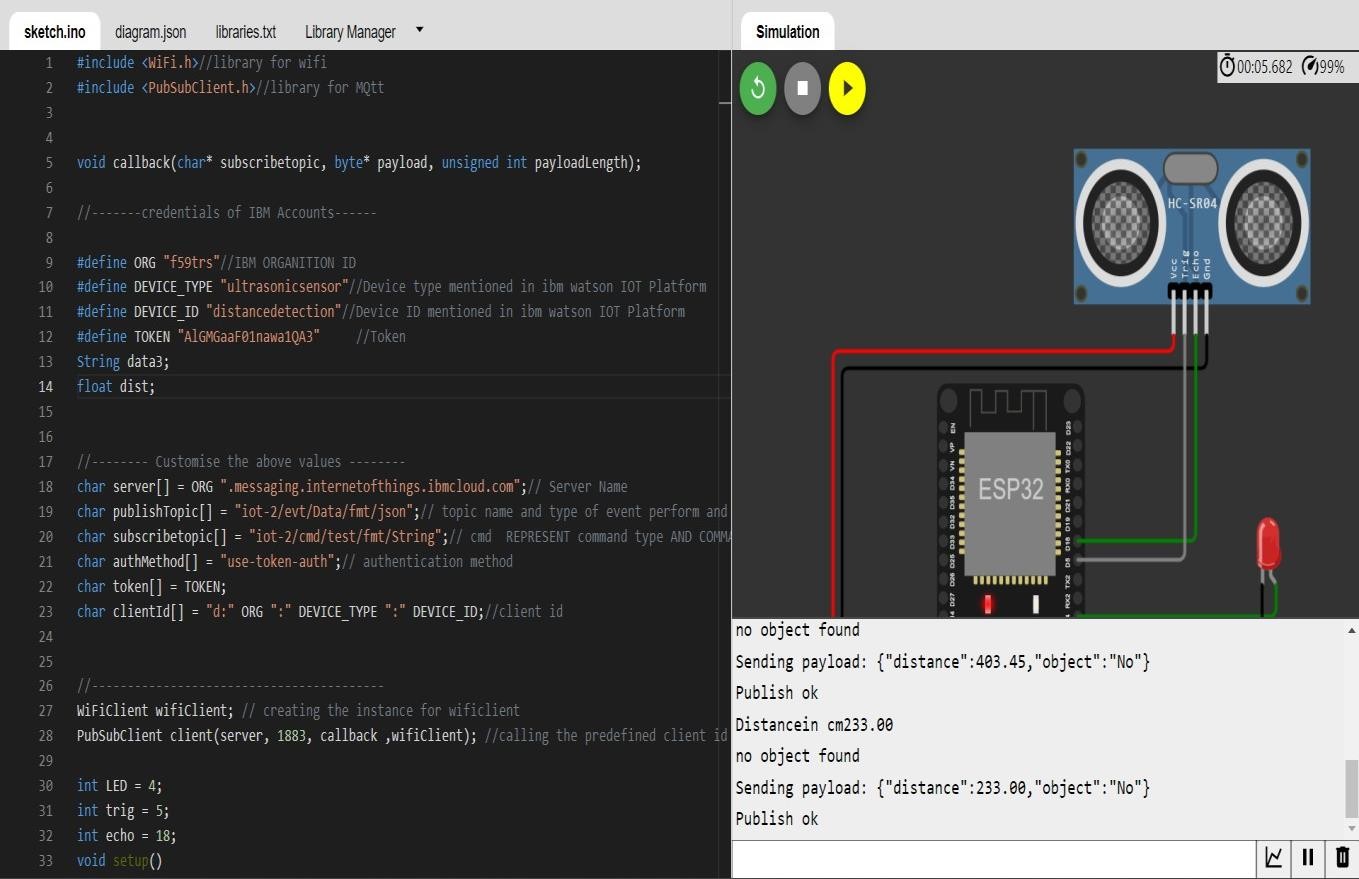
// digitalWrite(LED,LOW);

// } data3="";

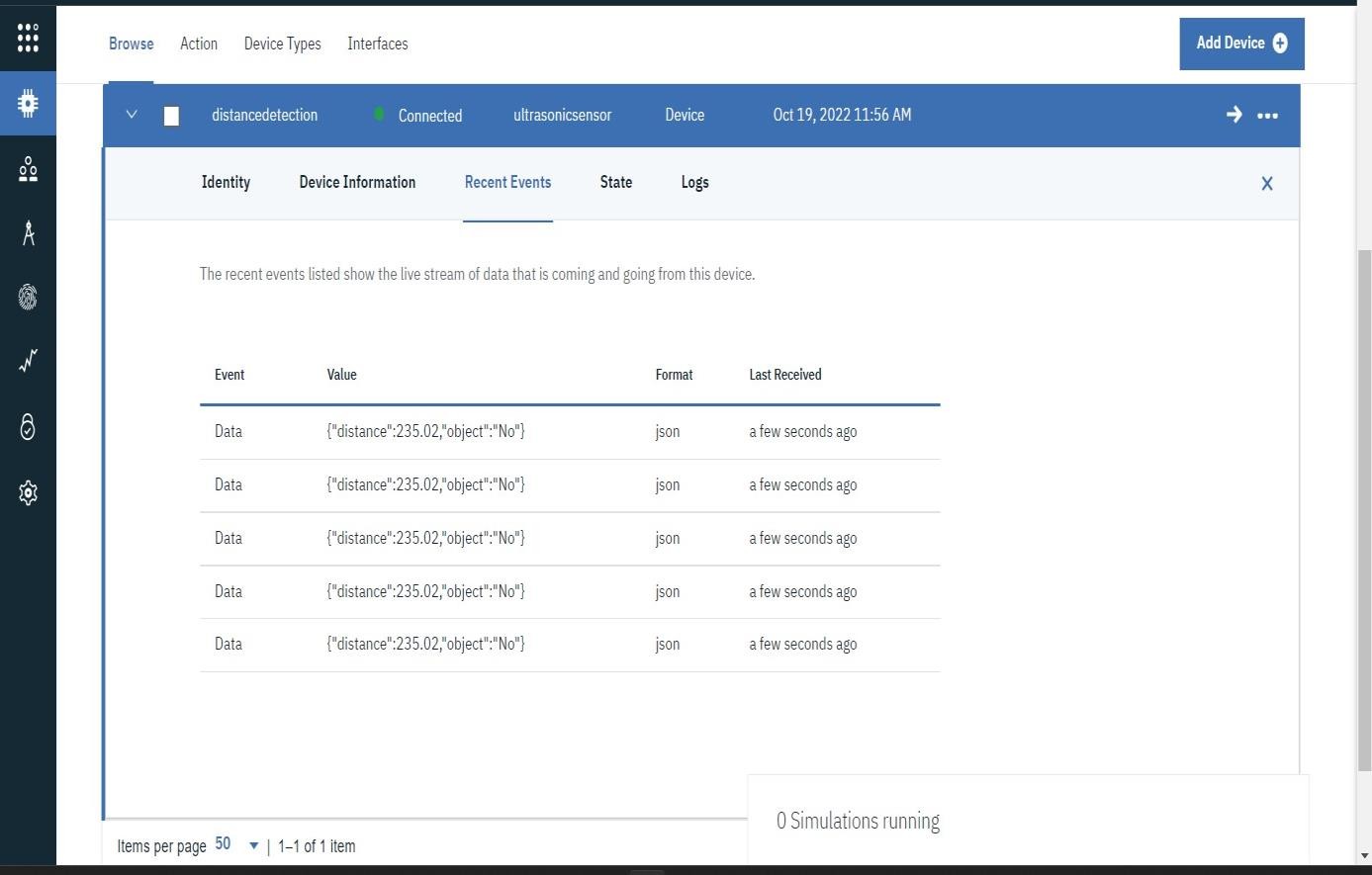
}

**OUTPUT:**

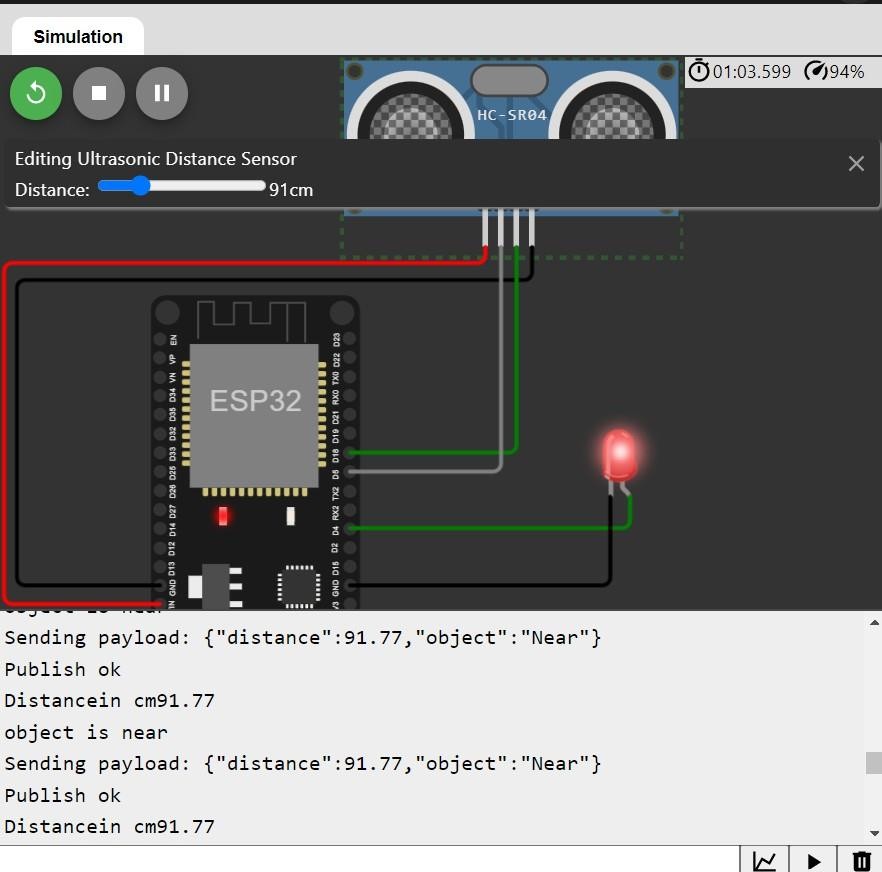
**When object is not near to the ultrasonic sensor**



**Data sent to the IBM cloud device when the object is far**



**When object is nearer to the ultrasonic sensor**



**Data sent to the IBM cloud device when the object is near**

